

```
> restart:with(plots):with(linalg);
```

Warning, the name changecoords has been redefined

Warning, the protected names norm and trace have been redefined and unprotected

[BlockDiagonal, GramSchmidt, JordanBlock, LUdecomp, QRdecomp, Wronskian, addcol, addrow, adj, adjoint, angle, augment, backsub, band, basis, bezout, blockmatrix, charmat, charpoly, cholesky, col, coldim, colspace, colspan, companion, concat, cond, copyinto, crossprod, curl, definite, delcols, delrows, det, diag, diverge, dotprod, eigenvals, eigenvalues, eigenvectors, eigenvects, entermatrix, equal, exponential, extend, ffgausselim, fibonacci, forwardsub, frobenius, gausselim, gaussjord, geneqns, genmatrix, grad, hadamard, hermite, hessian, hilbert, htranspose, ihermite, indexfunc, innerprod, intbasis, inverse, ismith, issimilar, iszero, jacobian, jordan, kernel, laplacian, leastsqrs, linsolve, matadd, matrix, minor, minpoly, mulcol, mulrow, multiply, norm, normalize, nullspace, orthog, permanent, pivot, potential, randmatrix, randvector, rank, ratform, row, rowdim, rowspace, rowspan, rref, scalarmul, singularvals, smith, stackmatrix, submatrix, subvector, sumbasis, swapcol, swaprow, sylvester, toeplitz, trace, transpose, vandermonde, vecpotent, vectdim, vector, wronskian]

[First Test, Calculus 2673, 9/20/2006

1.

```
> a:=[1,2,-3]:b:=[-1,3,4]:
```

i.

```
> b1 := dotprod(a,b)/(norm(a,2))^2*a;b2:=b-b1;
```

$$b1 := \begin{bmatrix} -\frac{1}{2} \\ -1 \\ \frac{3}{2} \end{bmatrix}$$

$$b2 := \begin{bmatrix} -\frac{1}{2} \\ 4 \\ \frac{5}{2} \end{bmatrix}$$

```
> dotprod(b1,b2); # check it
```

ii Find the lengt of a+b

```
> norm(a+b,2);
```

$$\frac{0}{\sqrt{26}}$$

iii. find angle between b and a

```
> arccos(dotprod(a,b)/(norm(a,2)*norm(b,2)));evalf(%);
```

```
>
```

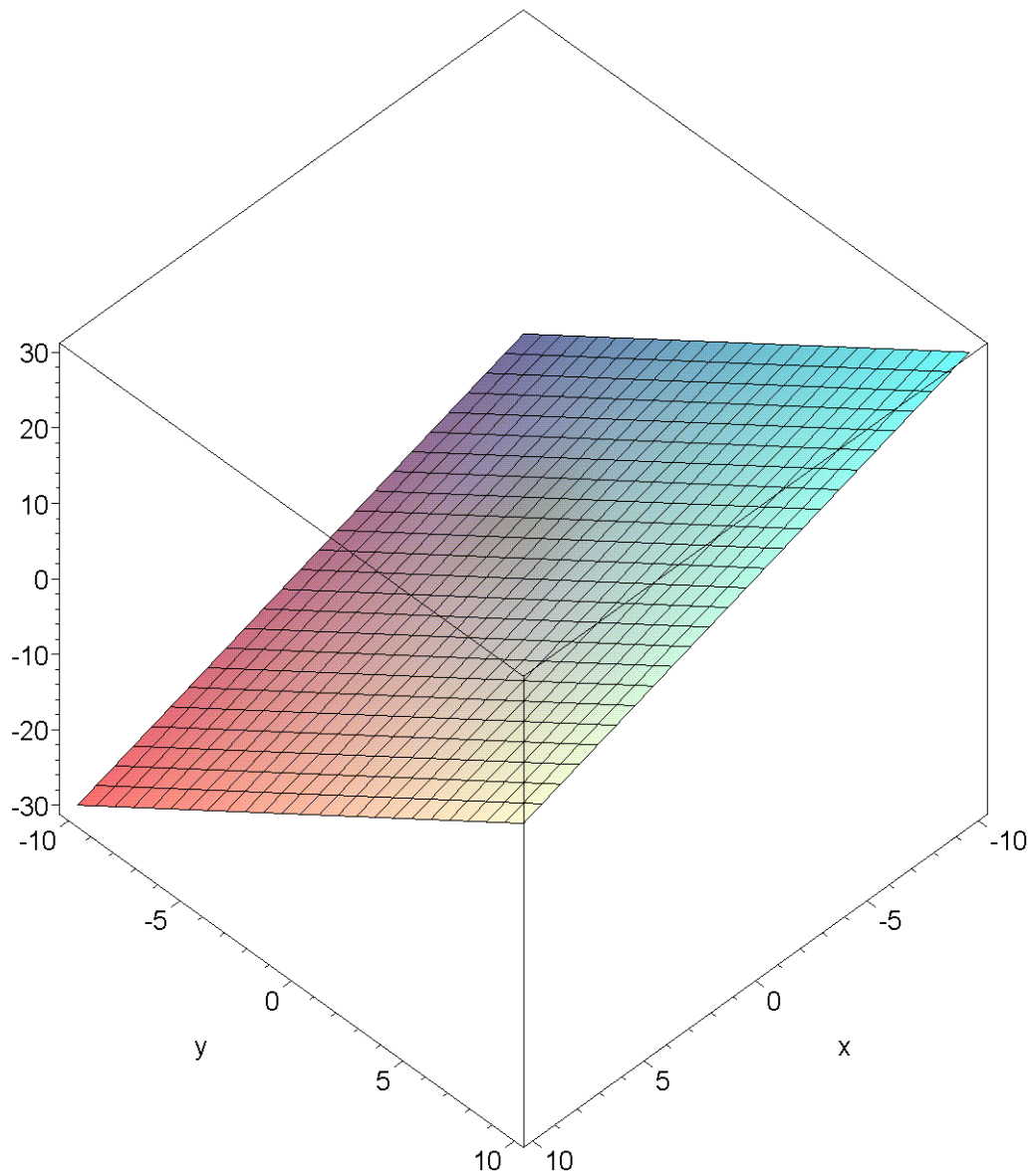
$$\pi - \arccos\left(\frac{\sqrt{14}\sqrt{26}}{52}\right)$$

$$1.946470418$$

```
> crossprod(a,b); # 4
```

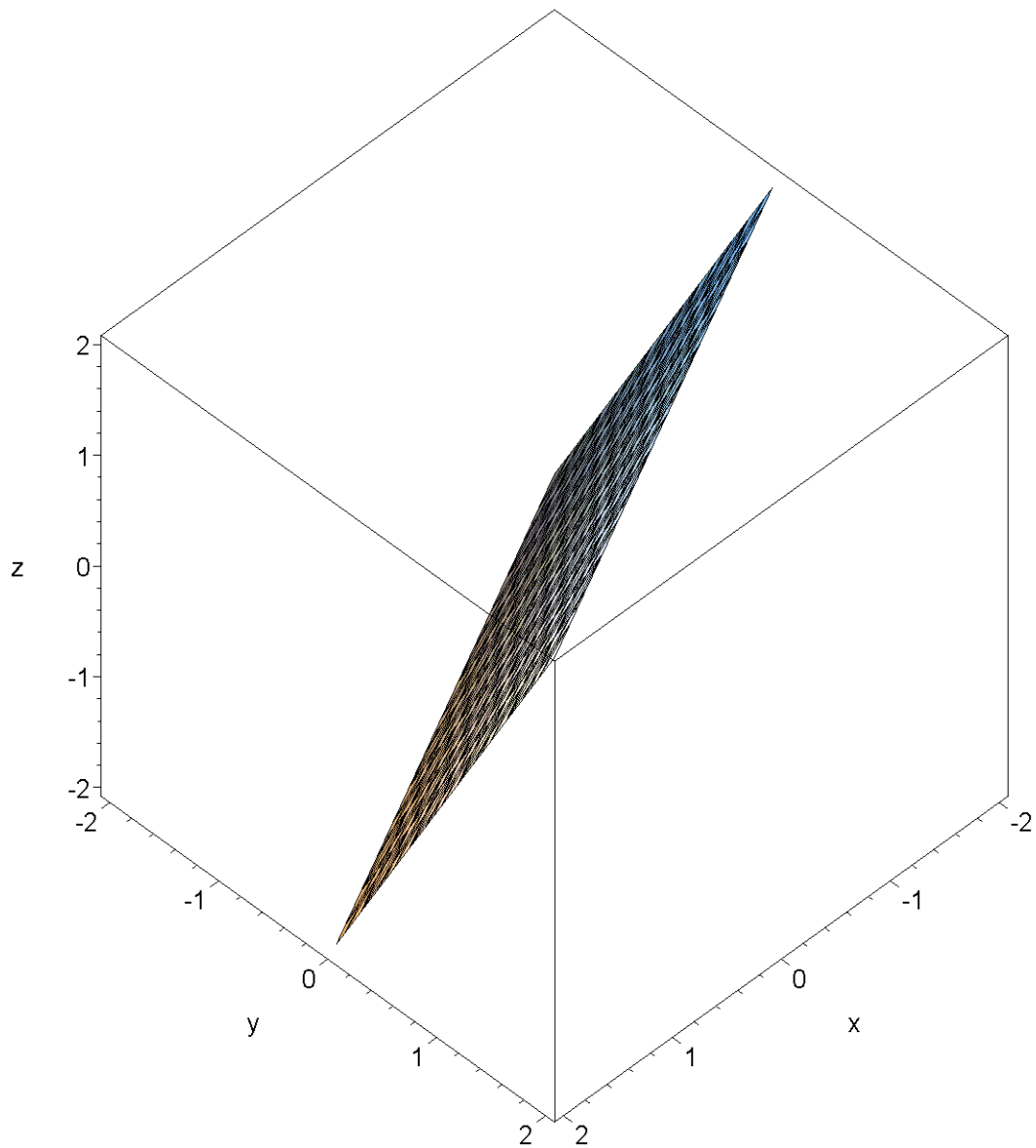
problem II

```
[17, -1, 5]
> A:=[ 1,1,1];B:=[3,2,1]; C:=[1,2,3];
      A := [1, 1, 1]
      B := [3, 2, 1]
      C := [1, 2, 3]
> BA:= B-A; CA:= C- A; n:= crossprod(BA,CA);
      BA := [2, 1, 0]
      CA := [0, 1, 2]
      n := [2, -4, 2]
Find the equation of the plane .
> R:=vector([x,y,z]);
      R := [x, y, z]
> u:=dotprod(R,n);k :=(dotprod(n,A)); # direction and konstant
      u := 2 x - 4 y + 2 z
      k := 0
> u = k; # equation of the plane
      2 x - 4 y + 2 z = 0
> plot3d(2*y-x,x=-10..10,y=-10..10,axes = boxed);# plot it
```



```
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```

```
> implicitplot3d(2*x-4*y+2*z=0, x=-2..2, y=-2..2, z=-2..2,  
axes=boxed);
```



2. a plane through (1,1,2) and perpendicular to the line

> `n:=[1,1/2,1/3]; # normal vector of plane`

$$n := \left[1, \frac{1}{2}, \frac{1}{3} \right]$$

> `P:=[1,1,2];R:=vector([x,y,z]);#P is the point`

$$P := [1, 1, 2]$$

> `u:=dotprod(R,n);k :=dotprod(n,P);`

$$u := x + \frac{y}{2} + \frac{z}{3}$$

$$k := \frac{13}{6}$$

```
> u=k; # equation of plane
```

$$x + \frac{y}{2} + \frac{z}{3} = \frac{13}{6}$$

```
3 find the point of intersection
```

```
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```

```
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```

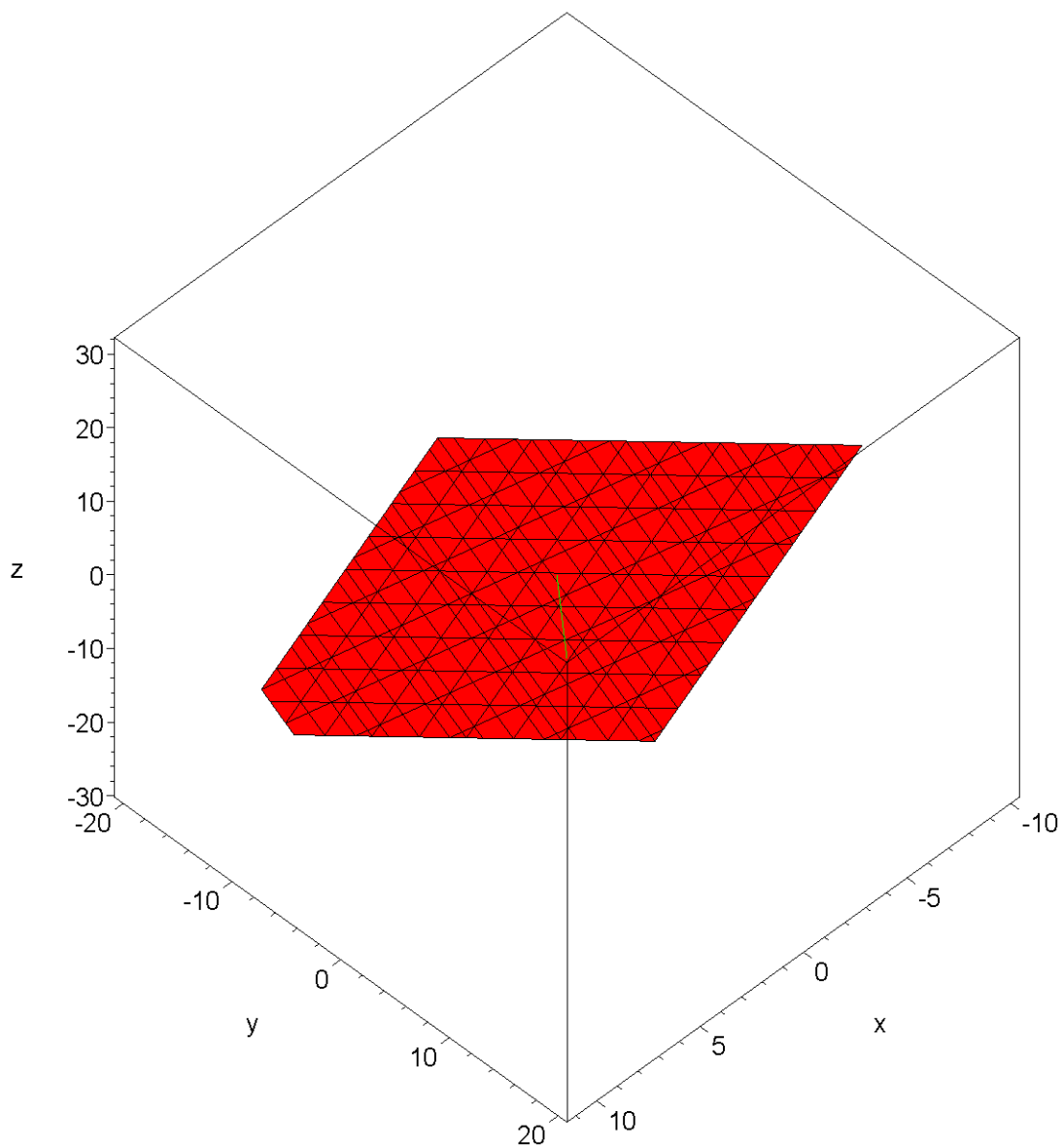
```
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```

$$7t + 3 = 3$$

```
> plot1 :=implicitplot3d( 2*x + y + z=3, x= -10..10, y= -10..10,z=
-10..10,color = red,axes = boxed):
```

```
> line1:=spacecurve([t+1,2*t,3*t+1],t=-10..10,color=green,axes=box):
```

```
> display3d(plot1,line1); # ok now the point
```



```
> subs( x=t+1,y=2*t,z=3*t+1, 2*x+y+z=3);solve(%,t);
```

$$7t + 3 = 3$$

$$0$$

[4. Find the parametric equation of the line through $(-1,2,4)$ and $(1,2,1)$

```
> p:=[-1,2,4]:q:=[1,2,1]:
```

```
> lvex:=t*(p-q) + p;
```

$$lvex := t[-2, 0, 3] + [-1, 2, 4]$$

III Sketch

$$n := [3, 6, 2]$$

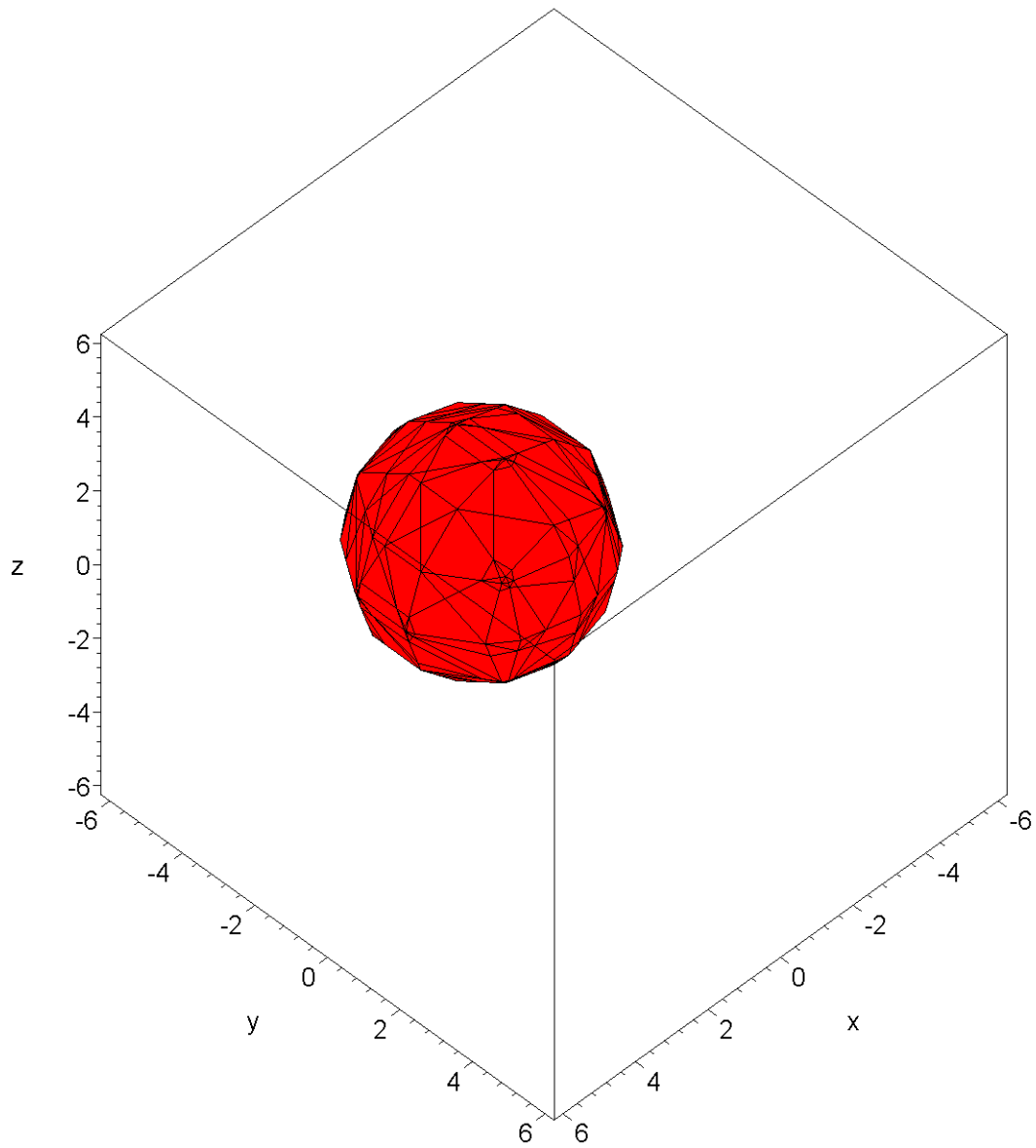
```
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```

```
implicitplot3d(x^2+y^2+z^2
```

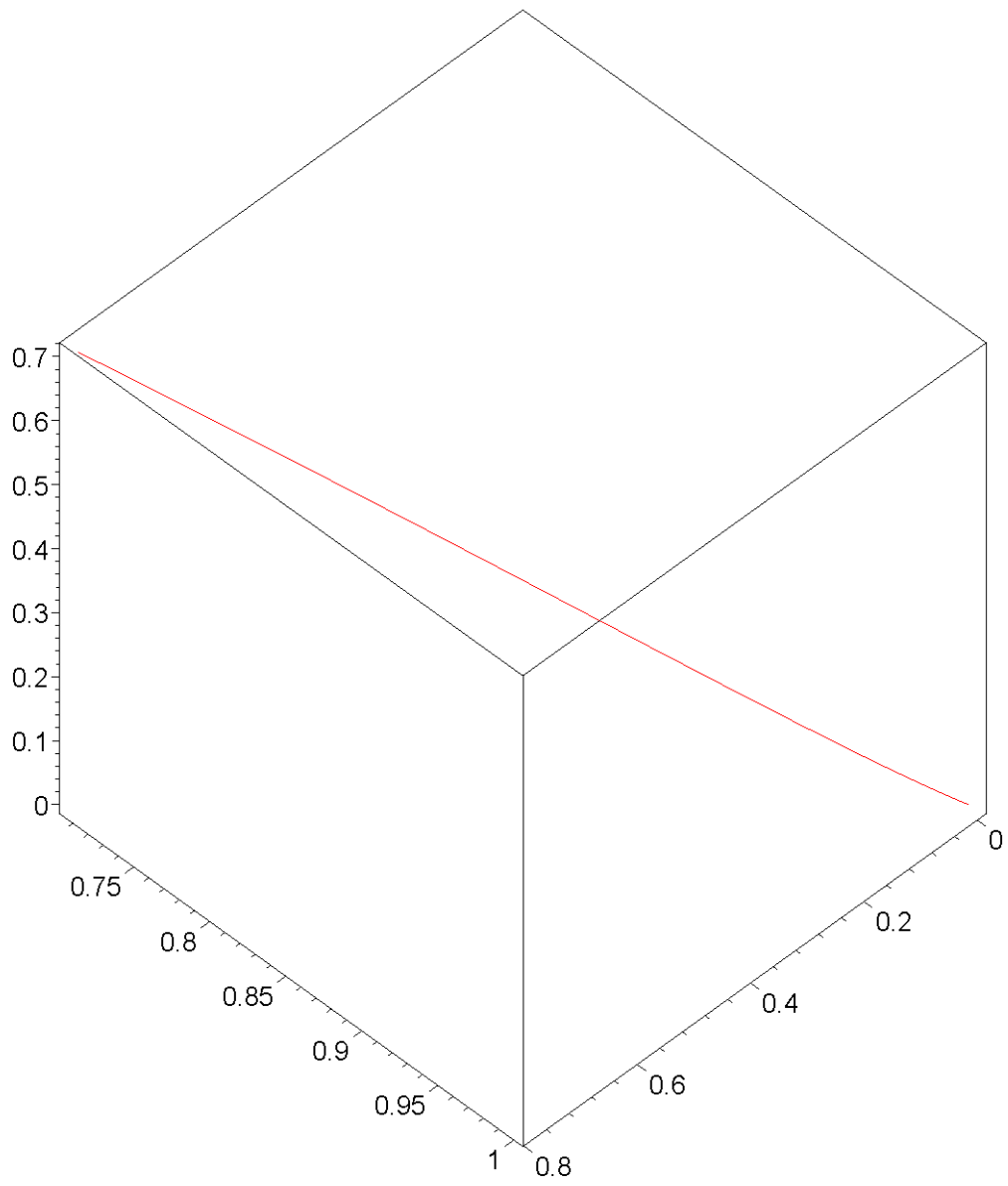
```
-4*x-4*z=0,x=-6..6,y=-6..6,z=-6..6,color = red,axes = boxed);
```

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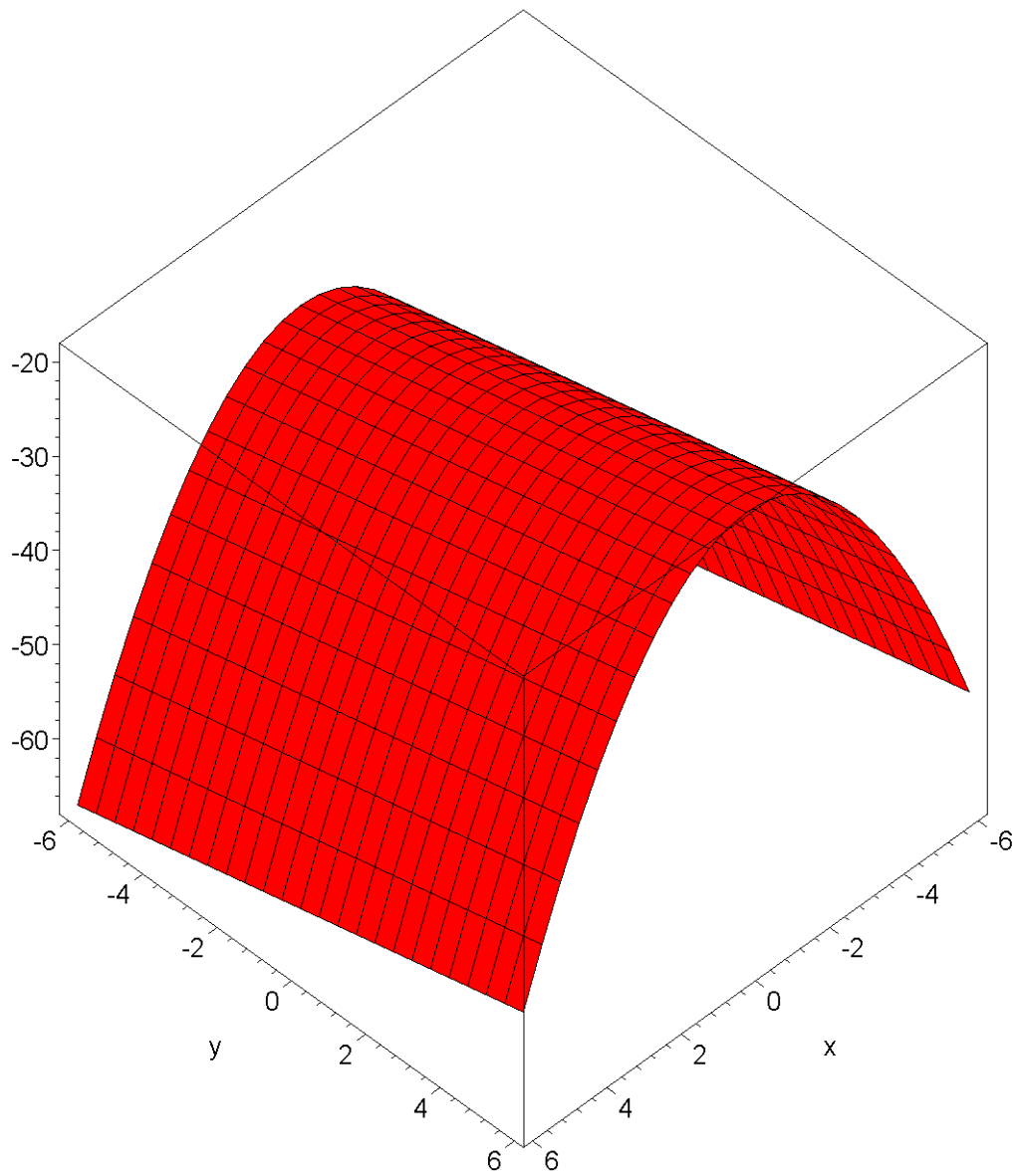
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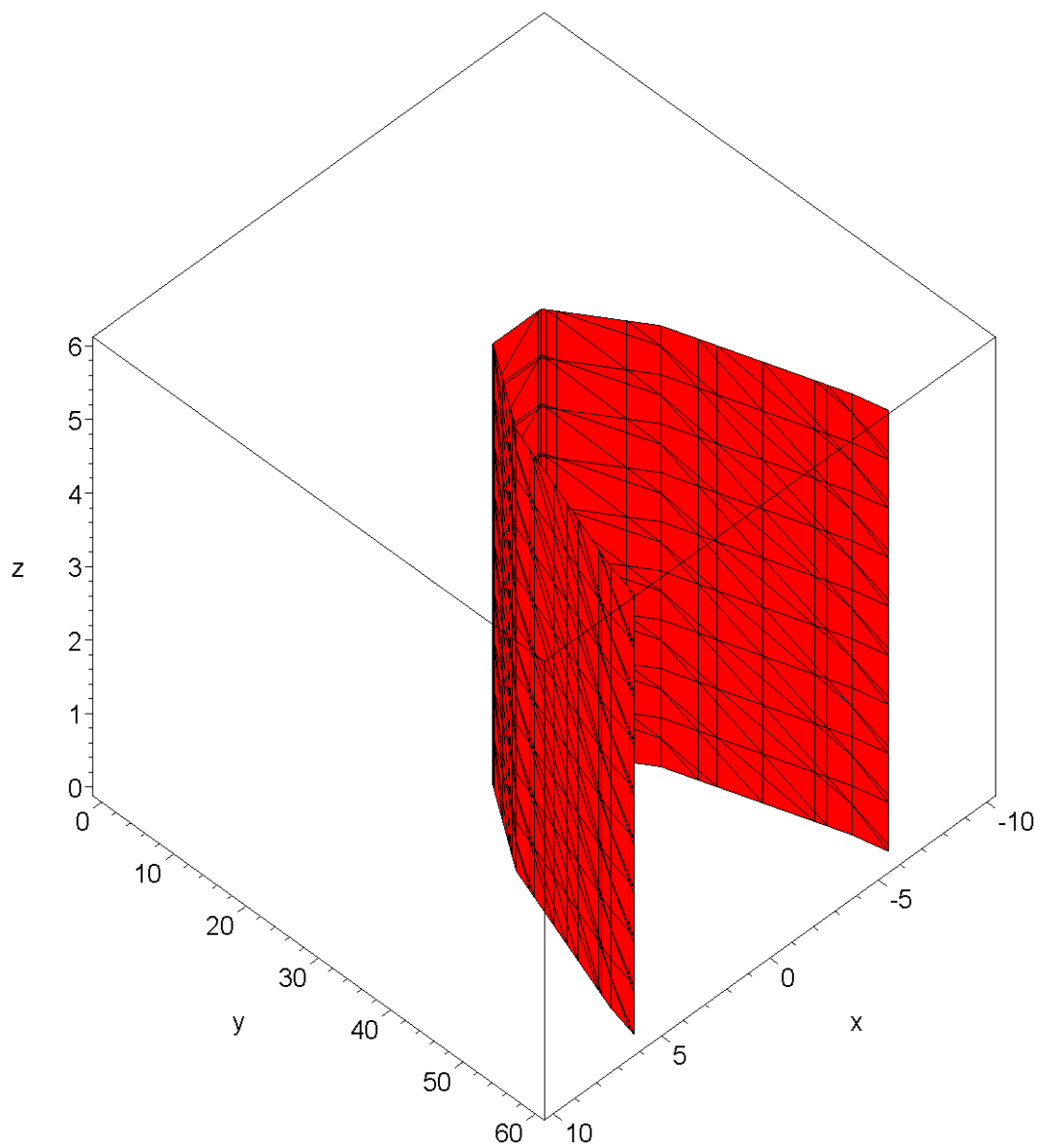
```
> spacecurve([t,cos(t),sin(t)],t=0..Pi/4,color=red,axes=box);
```



```
> plot3d(-x^2+y-25,x=-6..6,y=-6..6,color = red,axes = boxed);
```

```
> implicitplot3d(y - x^2 = 25, x= -10..10, y= 0..60, z= 0 .. 6,color  
= red,axes = boxed);
```



IV

```

> r:= t -> [4*cos(t),4*sin(t),t];
                                     r := t → [4 cos(t), 4 sin(t), t]
> v:= map((diff,r(t),t));
                                     v := [-4 sin(t), 4 cos(t), 1]
> a:= map(diff,v,t);
>
                                     a := [-4 cos(t), -4 sin(t), 0]
> T:= v/17;

```

```

[
    T :=  $\left[ -\frac{4}{17} \sin(t), \frac{4}{17} \cos(t), \frac{1}{17} \right]$ 
[ > N := map(diff,T,t);
    N :=  $\left[ -\frac{4}{17} \cos(t), -\frac{4}{17} \sin(t), 0 \right]$ 
[ > point0:=r(Pi/4); # last problem
    point0 :=  $\left[ 2\sqrt{2}, 2\sqrt{2}, \frac{\pi}{4} \right]$ 
[ > vector0:= subs(t=Pi/4,T);
    vector0 :=  $\left[ -\frac{4}{17} \sin\left(\frac{\pi}{4}\right), \frac{4}{17} \cos\left(\frac{\pi}{4}\right), \frac{1}{17} \right]$ 
[ > answer:= vector0*t + point0;
    answer :=  $\left[ -\frac{2\sqrt{2}}{17}, \frac{2\sqrt{2}}{17}, \frac{1}{17} \right] t + \left[ 2\sqrt{2}, 2\sqrt{2}, \frac{\pi}{4} \right]$ 
[ >
[ >
[ >

```